

National Aeronautics and Space Administration



Jet Propulsion Laboratory
California Institute of Technology

Soil Moisture Active Passive Mission SMAP

SMAPVEX12: PALS Measurements

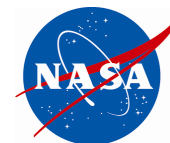
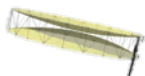
3rd Cal/Val Workshop

Nov. 14-16, 2012

A. Colliander, S. Yueh,
S. Chazanoff

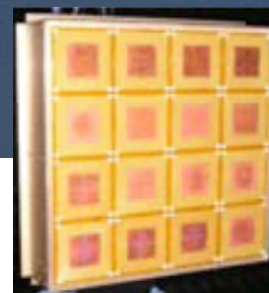
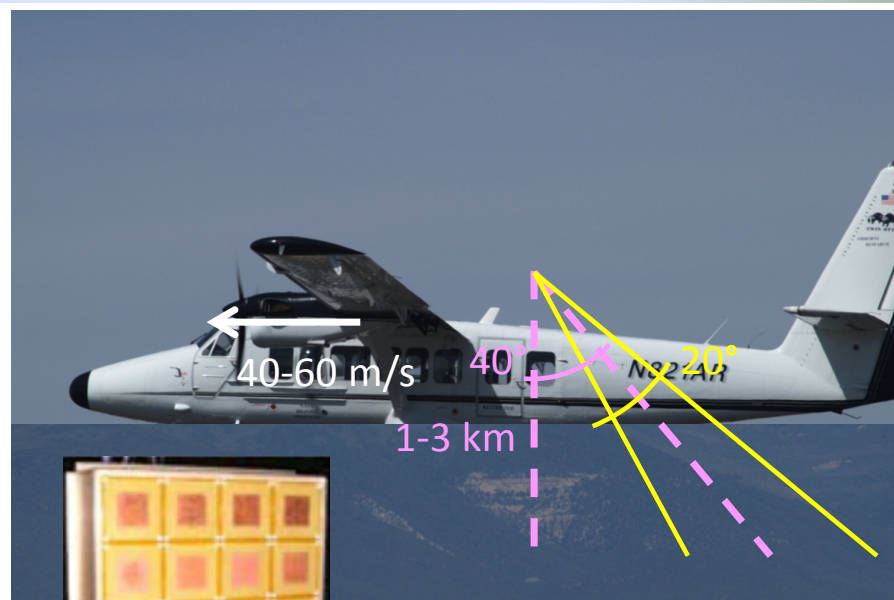
Jet Propulsion Laboratory,
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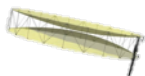


PALS Instrument

- Passive Active L-band System (PALS) functions as SMAP simulator
- L-band frequency
 - Radiometer: 1.41 GHz
 - Radar: 1.26 GHz
- View angle: 40°
- Operating altitude: 1-3 km
 - With 20° beamwidth 600-1500 m footprint
- Measurement resolution
 - Radiometer < 0.2 K
 - Radar < 0.2 dB
- Installation included a fast sampling digital backend for RFI studies
- Thermal infrared sensor
 - Nadir pointing, 2° beamwidth

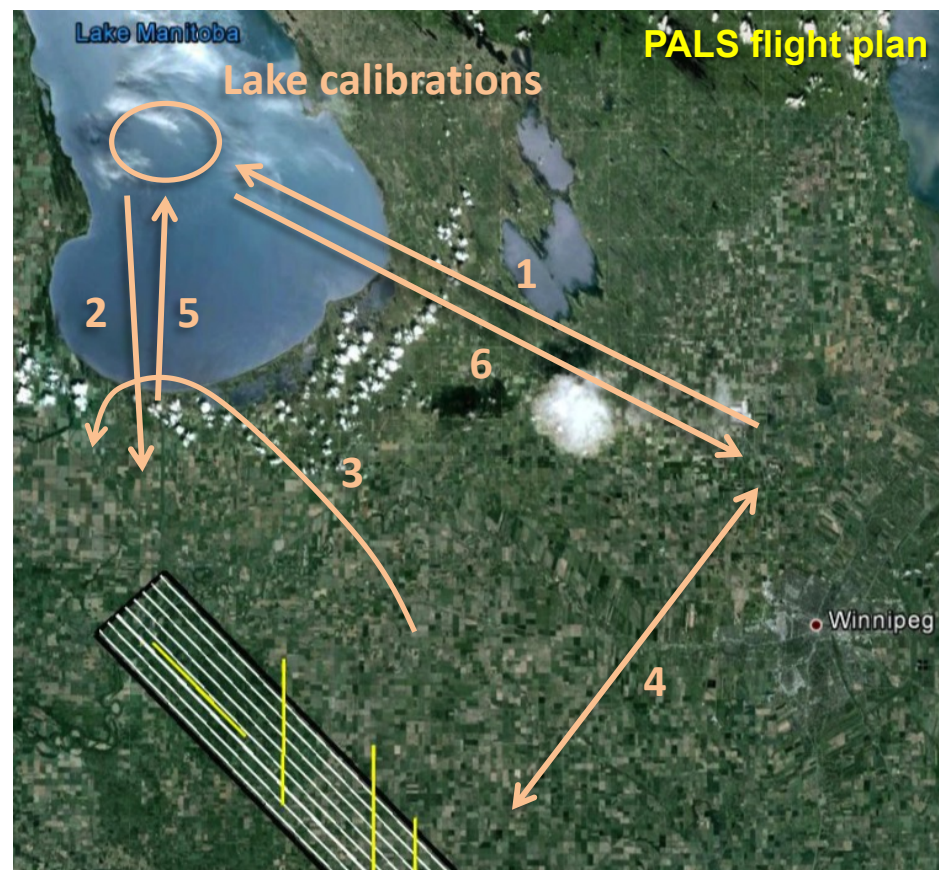


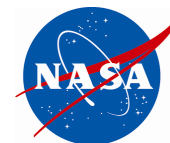
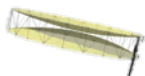
PALS antenna



SMAPVEX12 PALS Flight Plan

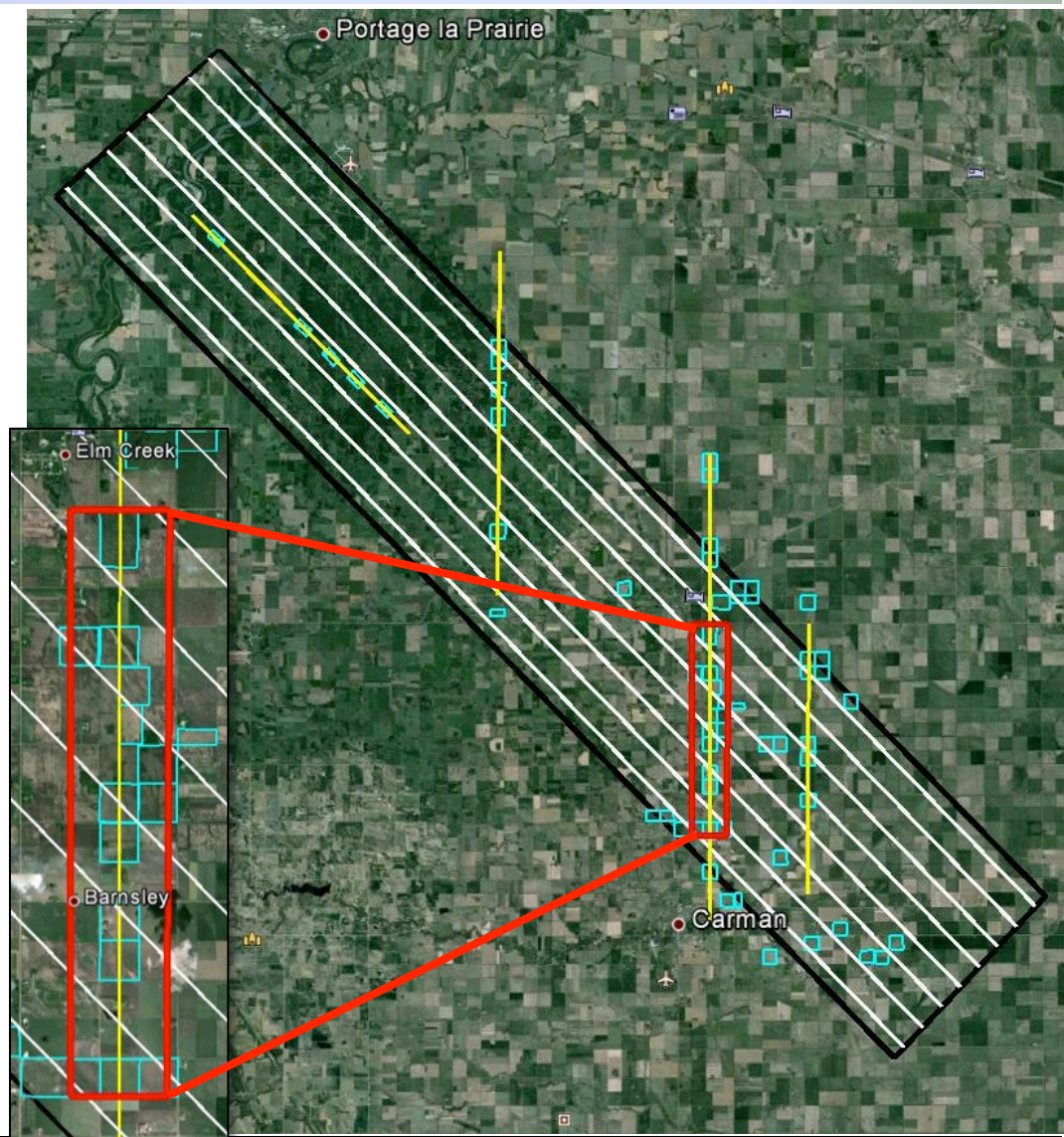
- PALS flight sequence (6-7 hours)
 - Take off from Winnipeg
 - Lake calibration
 - Low-altitude lines
 - High-altitude lines partially
 - Re-fuel at Winnipeg
 - Finish high-altitude lines
 - Lake Calibration
 - Landing at Winnipeg
- Operational notes
 - 17 flight days/100+ hours
 - 10 missed lines (out of total of $12 \times 17 = 204$): mostly due to weather conditions
 - Sun glint observed and avoided
 - Low RFI levels detected with a digital back-end

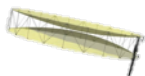




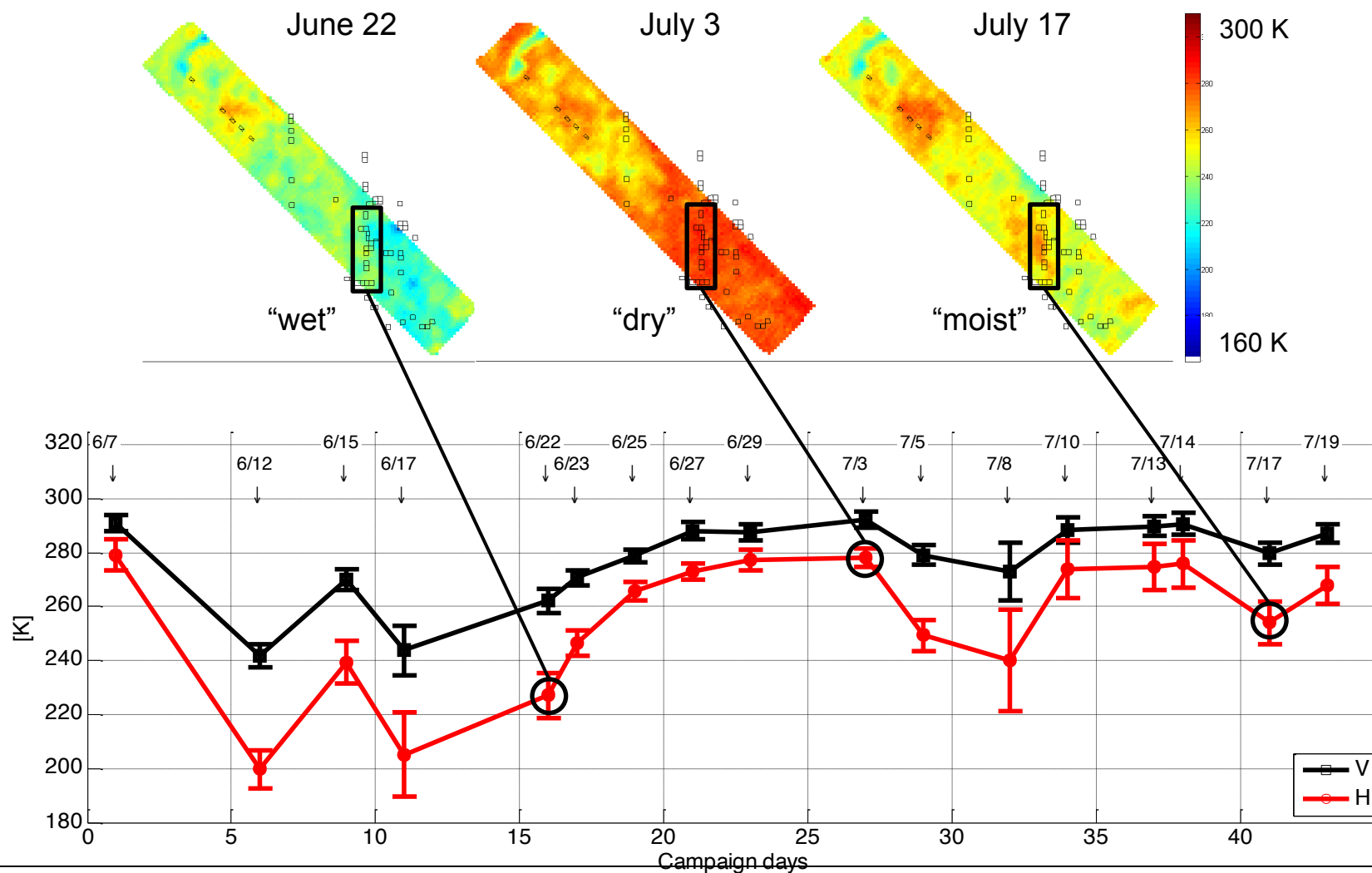
PALS results

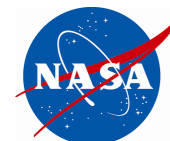
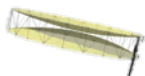
- PALS acquisitions were validated using a test area over a set of fields in the agriculture region
- Reference for low- and high-altitude measurements
- Soil moisture changes estimated from uncalibrated (at this point in time) in situ sensor readings





PALS radiometer results (1/3)





PALS radiometer results (2/3)

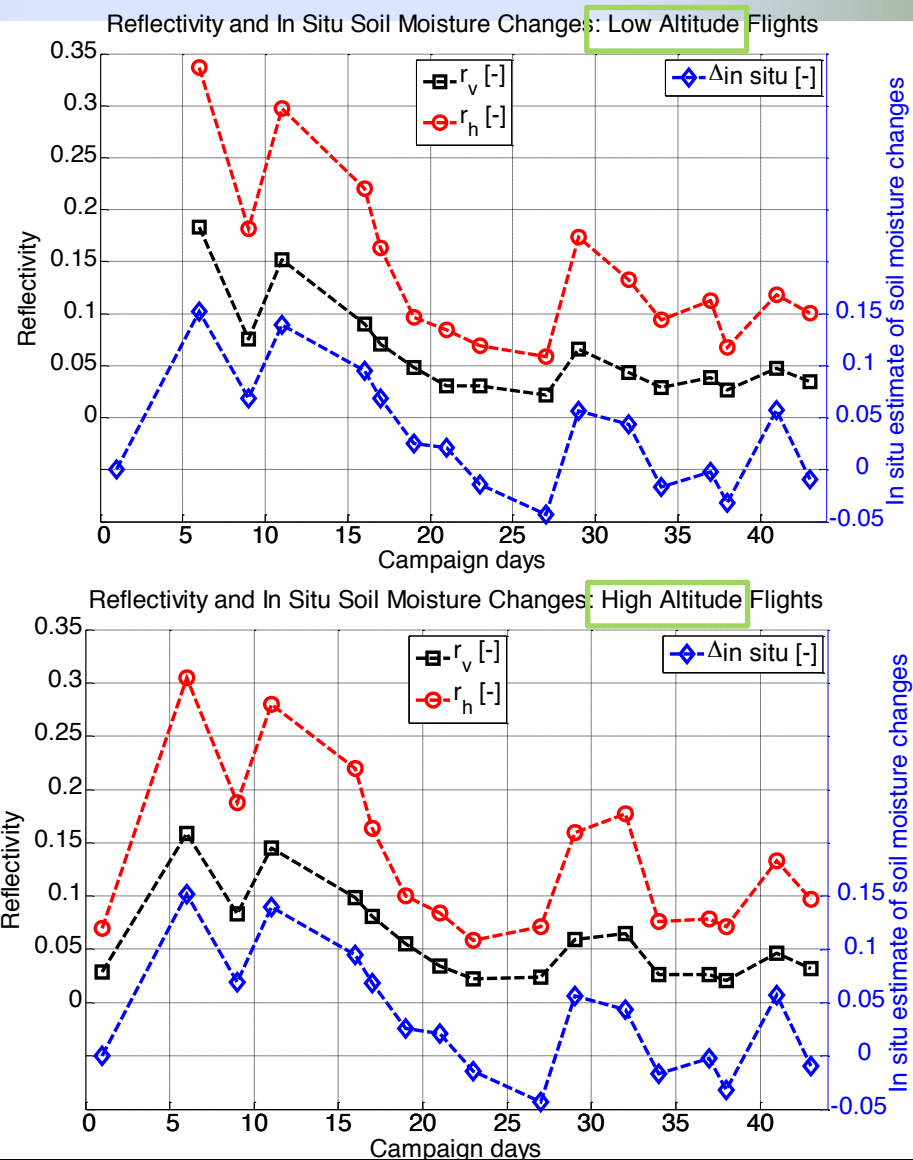
- Retrieve emissivity using the thermal infrared measurements
- Convert to reflectivity for straightforward comparison with soil moisture
- Time-series of airborne and in situ measurements matches well

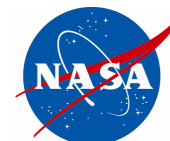
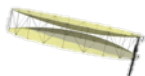
Emissivity

$$e_{lp}(\theta) = T_{B,p}(\theta) / T_{phys}$$

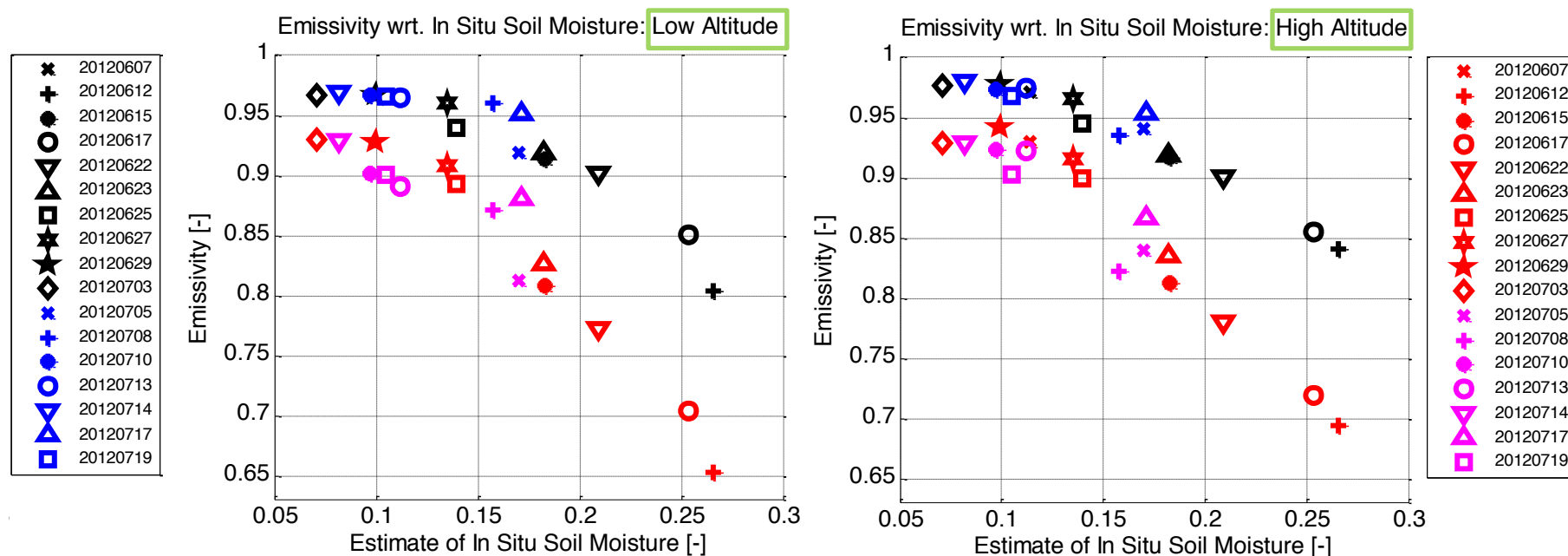
Reflectivity

$$r_{lp}(\theta) = 1 - e_{lp}(\theta)$$

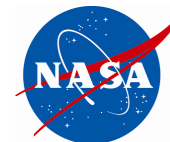
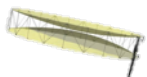




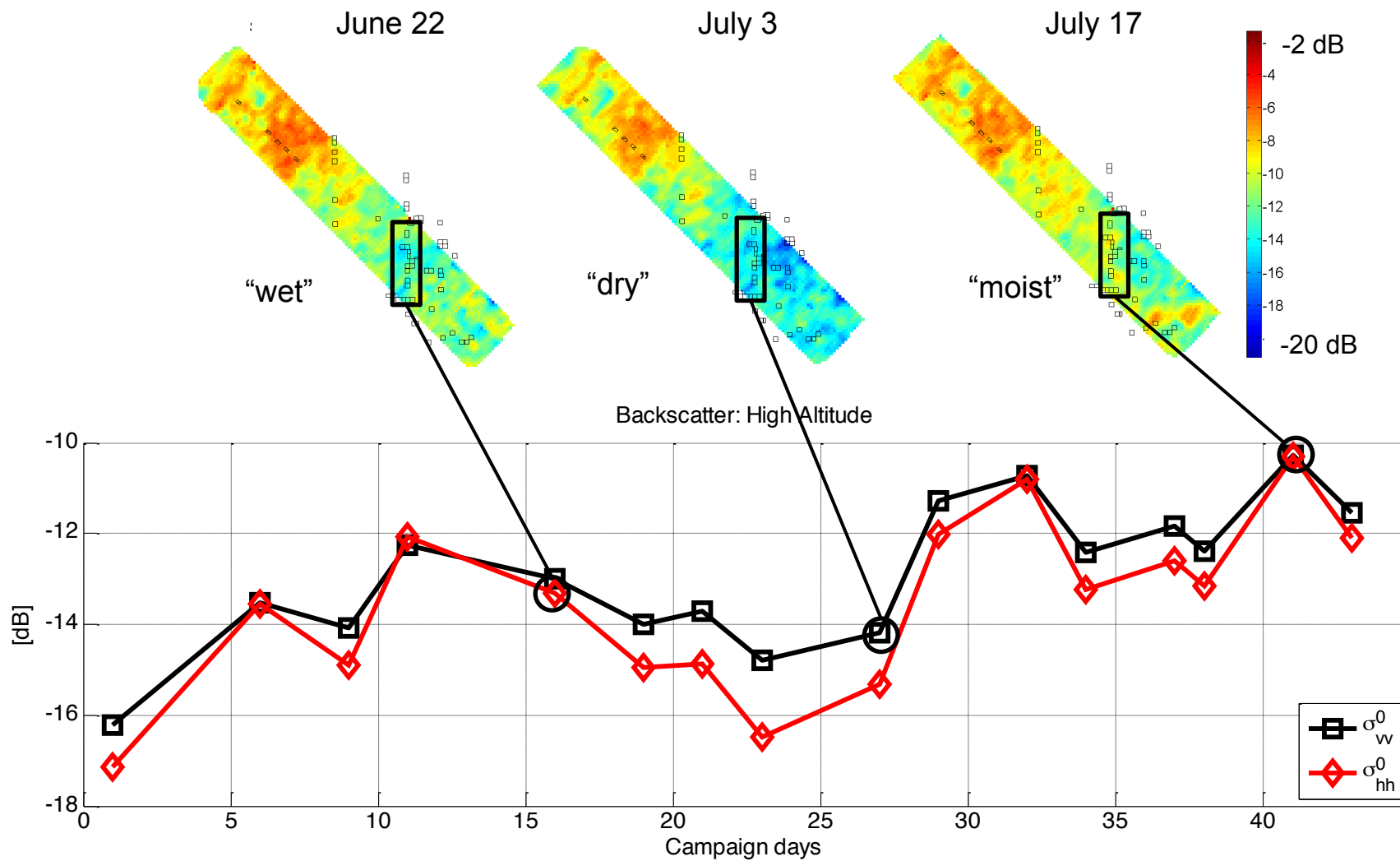
PALS radiometer results (3/3)

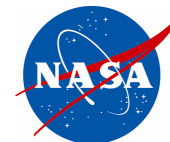
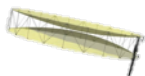


- Emissivity vs. (uncalibrated) soil moisture over the test area
- Correlation between airborne and in situ measurements as expected

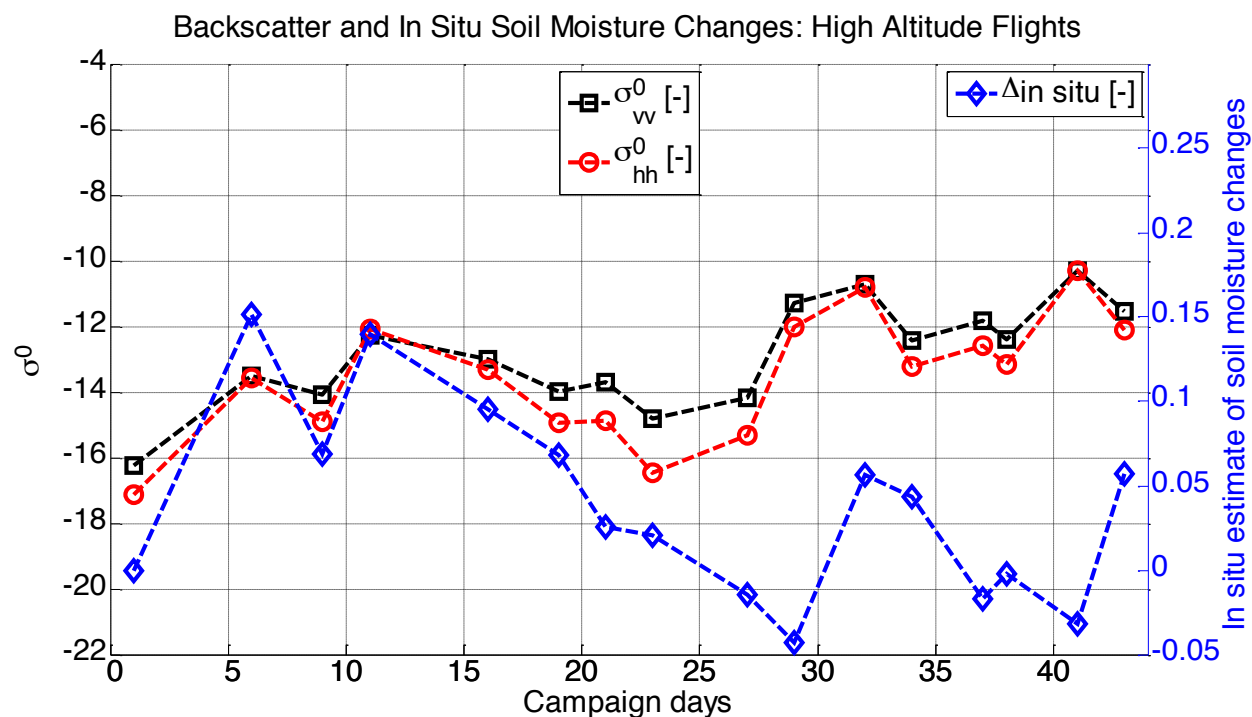


PALS radar results (1/2)

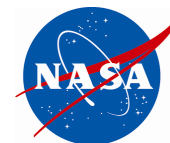
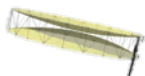




PALS radar results (2/2)

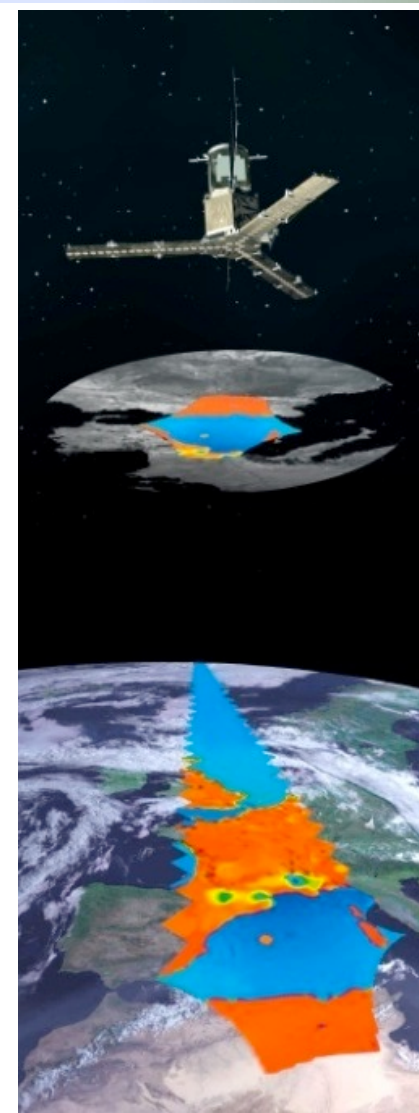
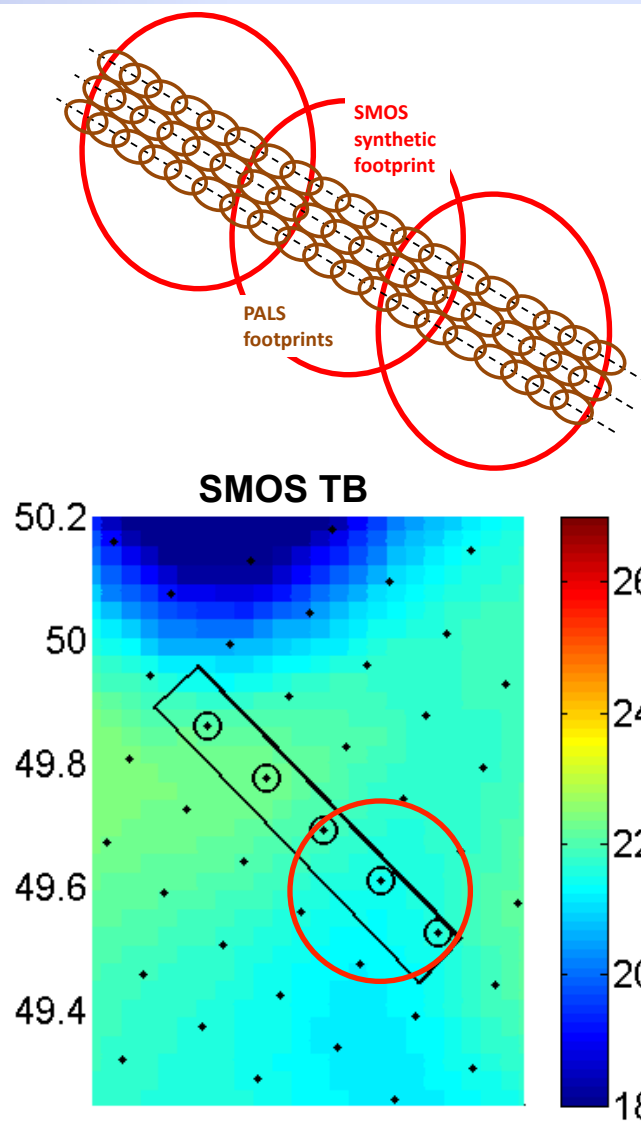


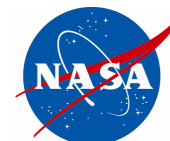
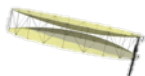
- Changes in backscatter match mostly the changes in soil moisture
- The effect of increasing vegetation can be seen as overall increasing trend in backscatter with respect to the soil moisture



PALS comparison to SMOS (1/2)

- Geophysical parameter retrieval algorithm development pre- and post-launch benefits from consistent airborne and spaceborne data sets
- Measurements did not cover full SMOS pixels (not the objective of the campaign)
- One SMOS footprint selected: centered mostly over the agriculture area
- Respective area of high-altitude PALS measurements analyzed

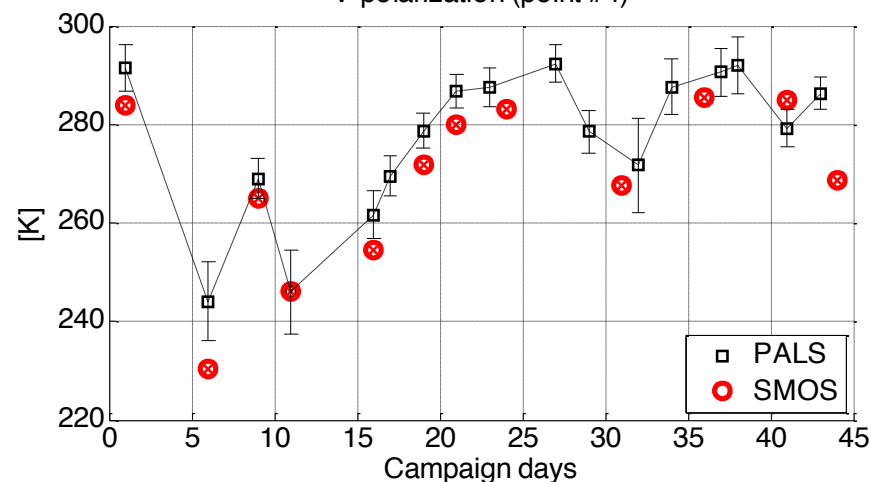




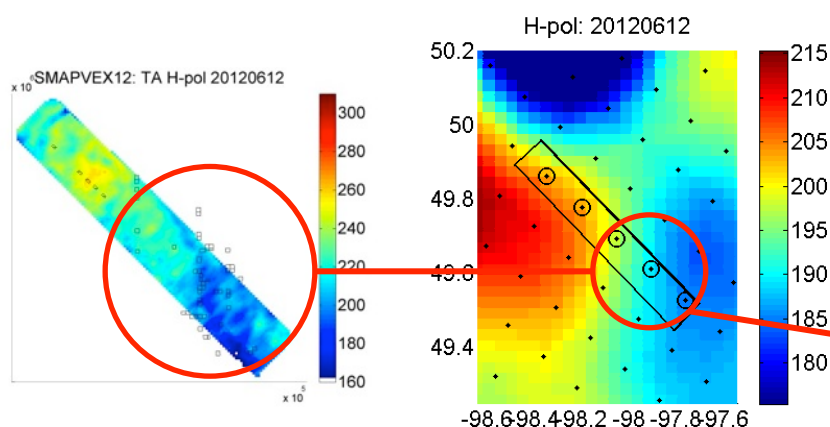
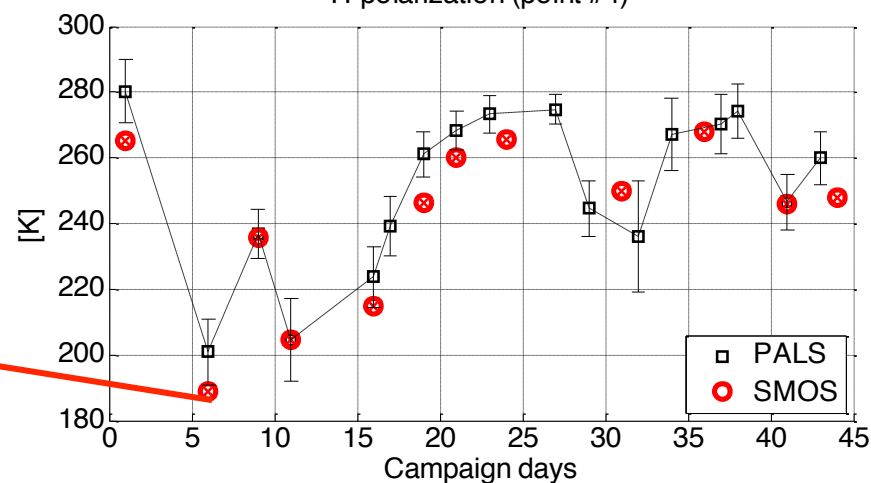
PALS comparison to SMOS (2/2)

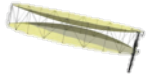
- Generally a very good agreement between the trends in the two measurements
- A few Kelvins bias between the measurements may be caused by different support areas of the measurements
- Values seen in the airborne measurements are representative to those seen from the orbit

Comparison of PALS and SMOS Antenna Temperatures
V-polarization (point #4)



Comparison of PALS and SMOS Antenna Temperatures
H-polarization (point #4)





Conclusions

- Initial comparisons of PALS acquisitions with in situ measurements and SMOS measurements show a good match indicating that the objective of the campaign was met and the PALS data can be used for SMAP soil moisture algorithm development, testing and validation