Soil Moisture Data Assimilation in the Canadian Land Data Assimilation System (CaLDAS)

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Objectives / Requirements for the new Land -Surface Modeling and Data Assimilation System

• Improve environmental predictions from Environment Canada's operational systems including :

• deterministic NWP systems (regional, global, LAM), ensemble prediction systems (regional, global), seasonal, climate, hydrology ...

• Provide accurate analysis of the current state of the land surface, including the following variables :

• soil moisture, snow conditions (coverage, water equivalent, density), temperatures, albedo, emissivity, vegetation characteristics (leaf area index and fractional coverage)

• Provide operational products that could be useful to other government departments, like for example :

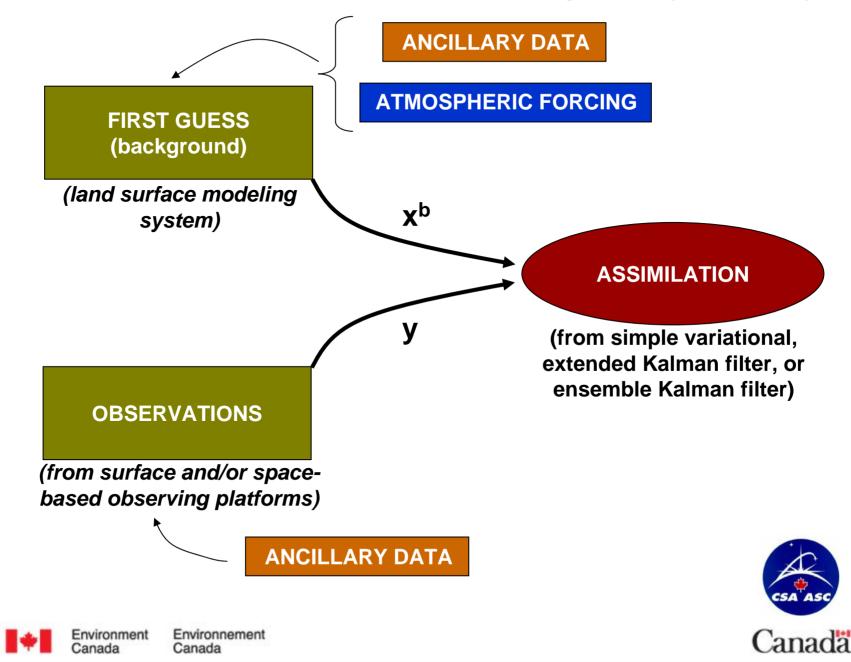
• Agriculture and Agri-Food Canada (AAFC), Natural Resources Canada (NRCan).







Canadian Land Data Assimilation System (CaLDAS)



Data Assimilation



Analysis equation

$$\mathbf{x}^{a} = \mathbf{x}^{b} + \underbrace{\mathbf{BH}^{T} \left[\mathbf{HBH}^{T} + \mathbf{R}\right]^{-1}}_{Gain Matrix} \underbrace{\left[\mathbf{y} - H\left(\mathbf{x}^{b}\right)\right]}_{Innovation Vector}$$

Keys to the success of data assimilation methods rests largely upon the accurate specification of the input error parameters.

Modeling of First-Guess Uncertainty : B Matrix

Initial conditions

Soil moisture Surface temperature Snow conditions

Land surface characteristics (ancillary data)

Vegetation characteristics (fraction coverage, LAI) Soil texture Albedo

Emissivity

orography

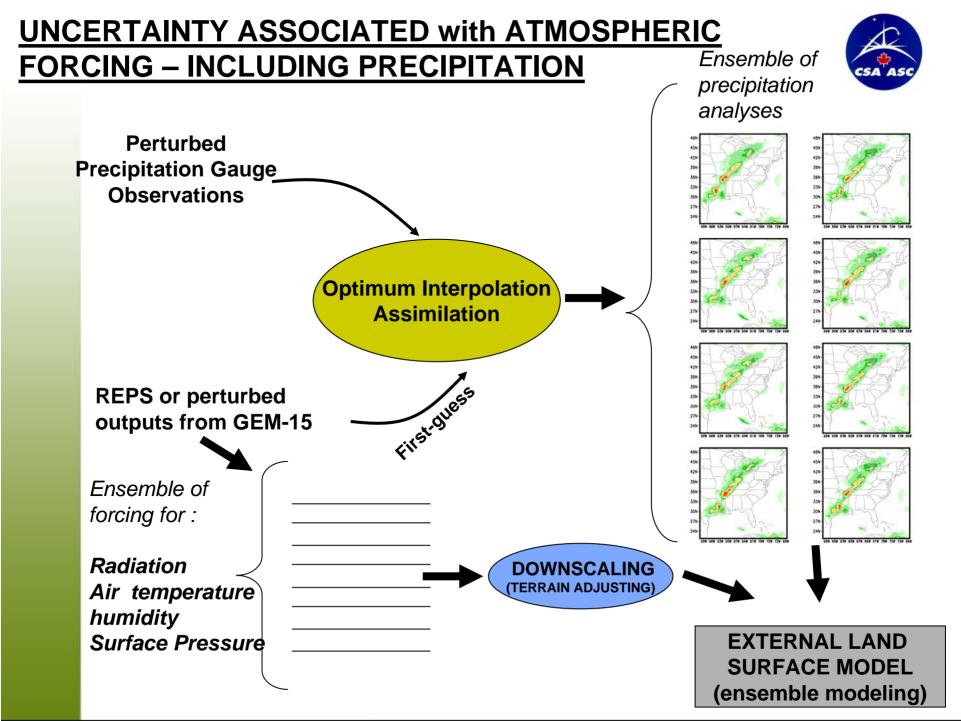
Atmospheric forcing

U, V, T, q, SW \downarrow , LW \downarrow , precipitation Land surface modeling

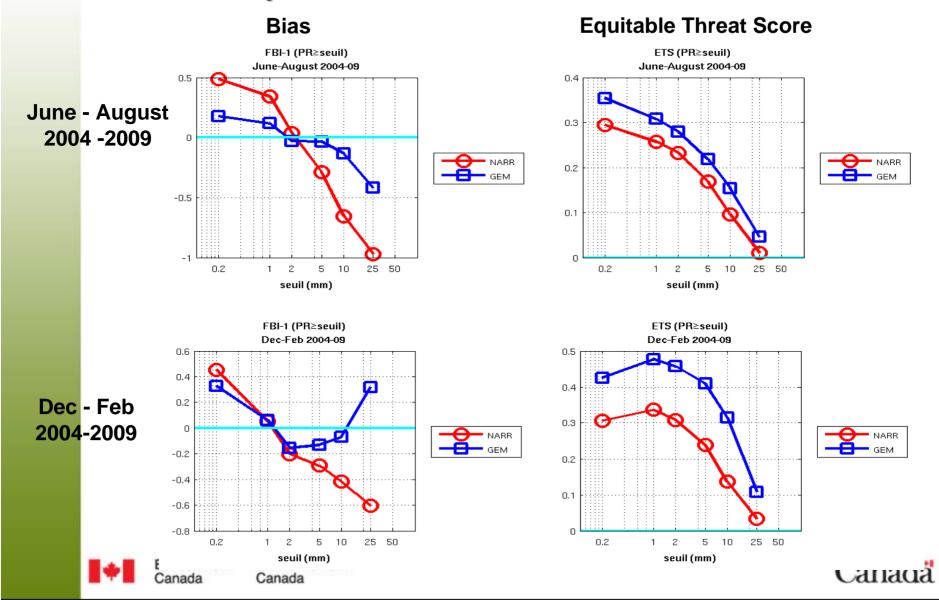


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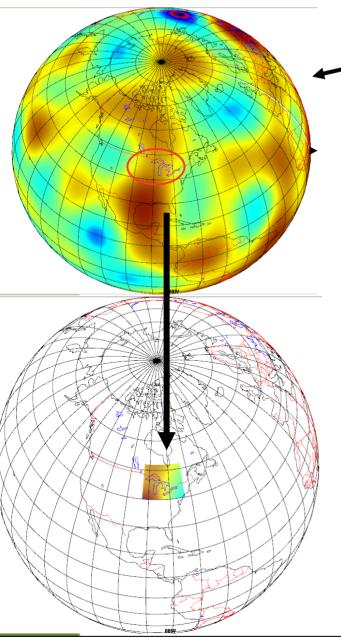


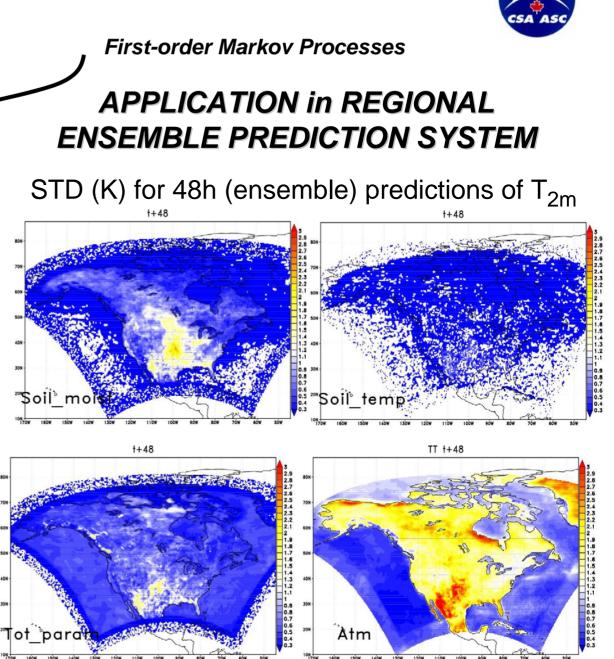
GEM-15 vs NARR (North American Regional Reanalysis) (6 –h Precipitation) Comparison with ~ 100 Manned Stations



UNCERTAINTY ASSOCIATED with LAND SURFACE CHARACTERISTICS

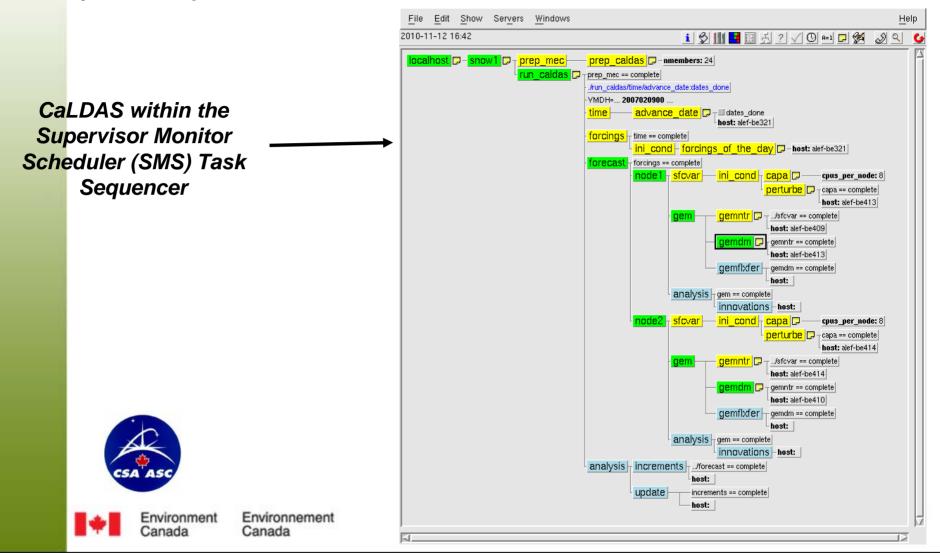




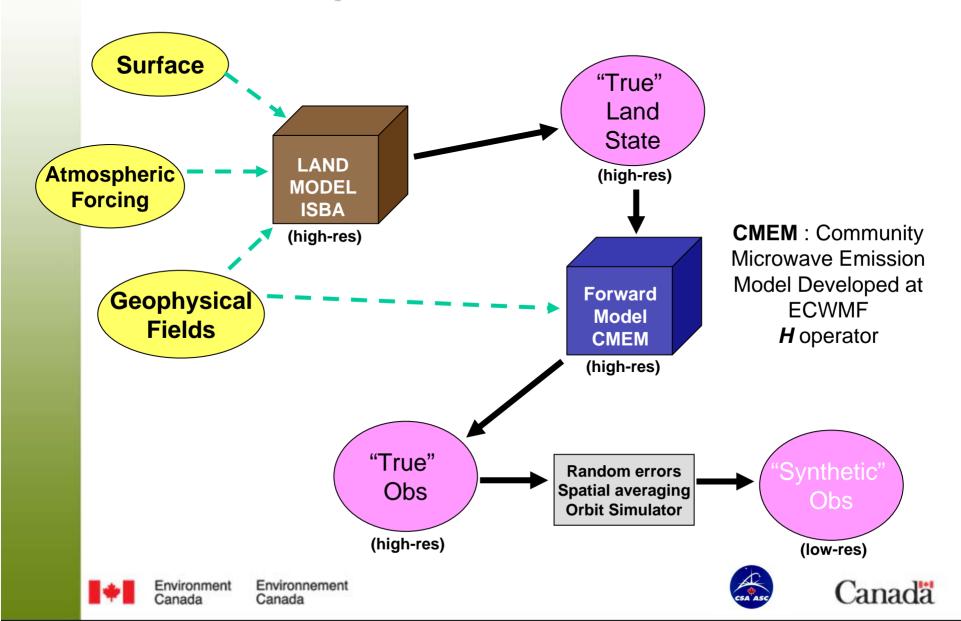


CaLDAS : Status

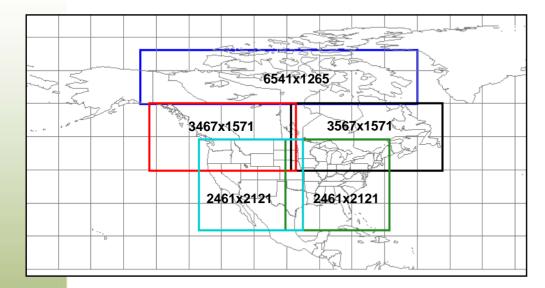
A first version of CaLDAS has been coded and developed. Both an Ensemble Kalman Filter (EnKF) version and a simplified 2D-Var version are available. Both of these versions have been tested within the context of synthetic experiments.

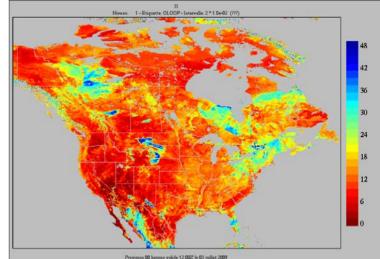


Synthetic Experiment Design (I) Generation of Synthetic "Truth" Observations



High-Resolution : Nature Run "Truth Run"





- 1-km resolution integrations of the ISBA landsurface model;
- Atmospheric forcing provided by short-range forecasts from the GEM-15 model;
- Geophysical fields generated from highresolution land-surface databases;
- •Time period : 30 March 2009 31 March 2010.
- North America : 5 separate integration grids



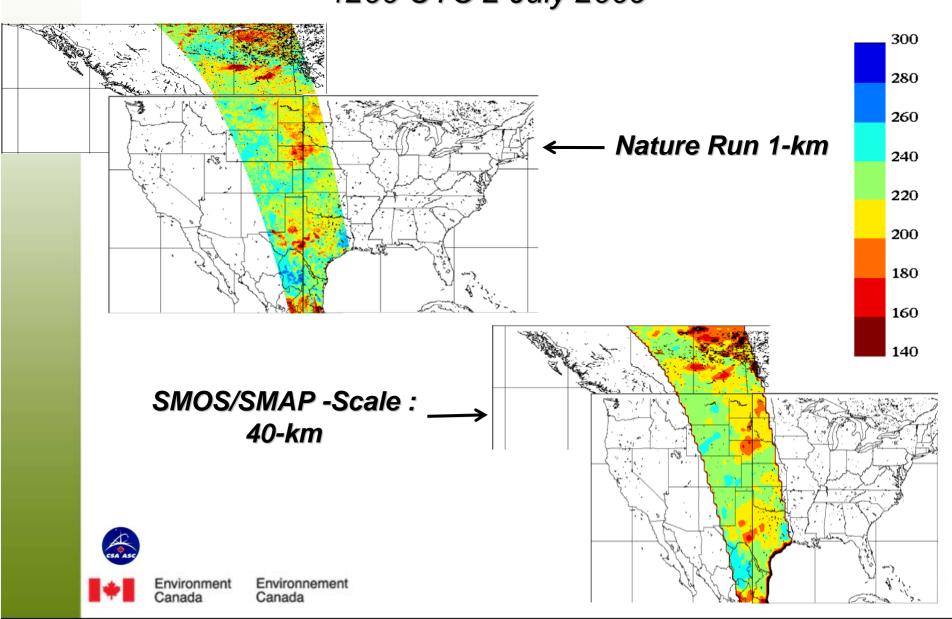
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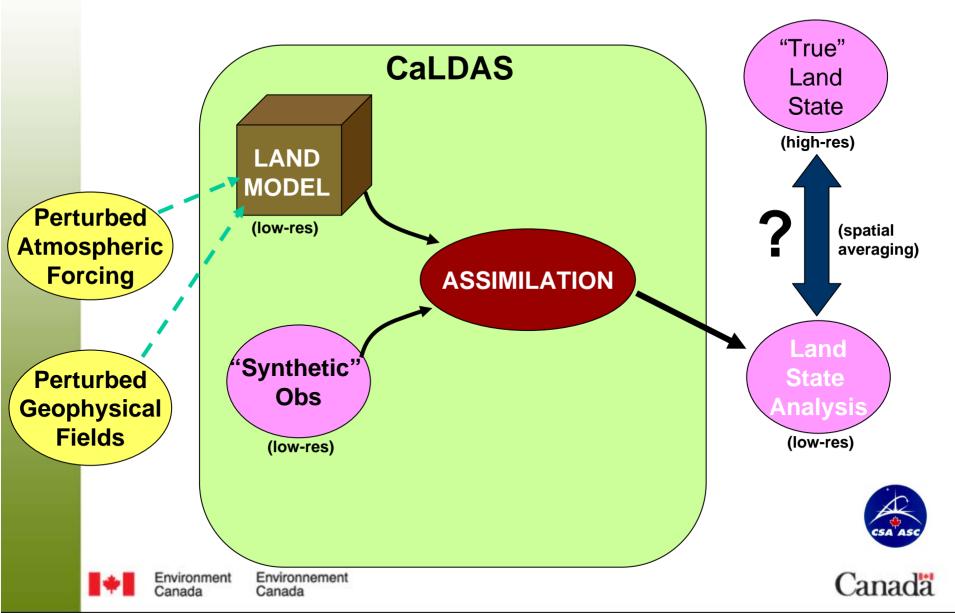
1200 UTC 3 July 2009 Superficial Soil Moisture [10-cm depth]



Brightness Temperatures (K) : Horizontal Polarization (40°) 1200 UTC 2 July 2009



Synthetic Experiment Design (II) EnKF Data Assimilation Run

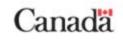


Synthetic Experiment-Specifications

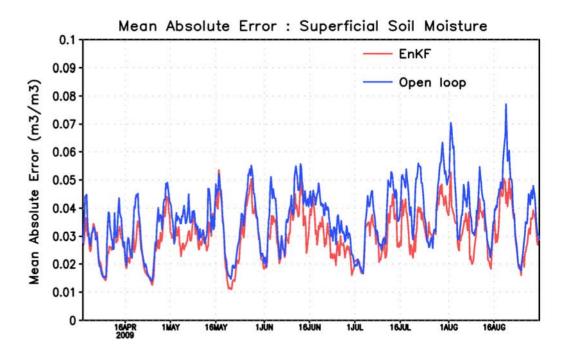
- **Assimilation grid**: 40-km resolution covering the eastern portion of North America.
- **Control variable**: Superficial soil moisture (10-cm depth).
- <u>Observations assimilated</u> : HH, VV polarization L-brightness temperatures at 40° incidence angle, spatially and temporally located using a SMOS-orbit simulator. Roughly a 2-3 day repeat cycle.
- **EnKF assimilation** run with 48 members.
- Each ensemble members is integrated with perturbed precipitation, radiation, air temperature derived from 30-42 hr GEM-15 forecasts.
- Surface albedo, vegetation fraction and leaf area index values were also perturbed as described.
- **Open loop integration** consists of one integration of the land-surface model.







Time series of domainaveraged soil moisture errors, considering only land points with very small water fractional coverage.)

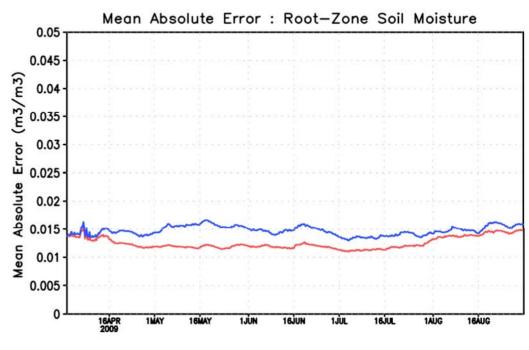


Root-zone soil moisture is improved by roughly 0.002- $0.003 \text{ m}^3 \text{ m}^{-3}$.

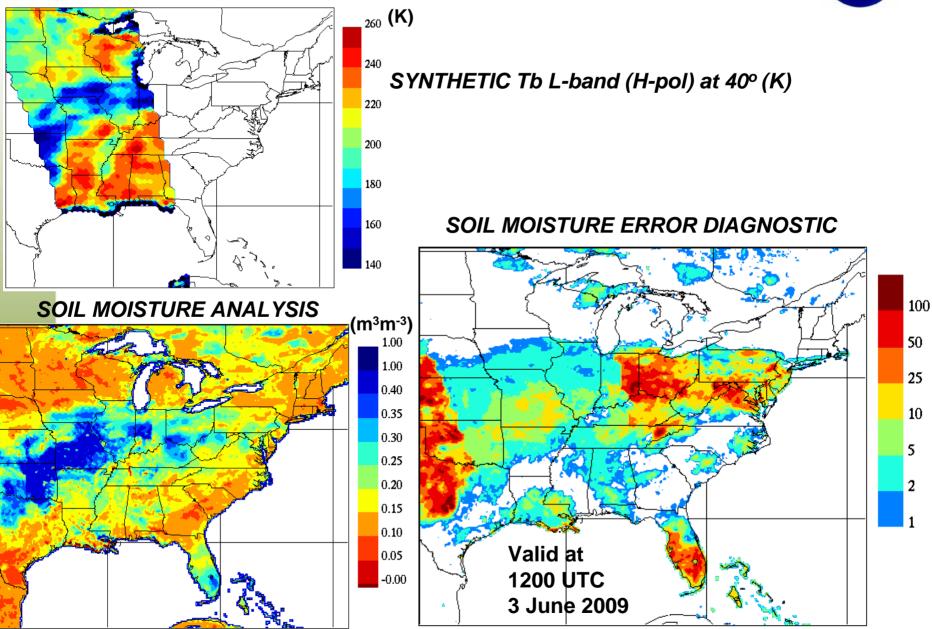


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SOIL MOISTURE ANALYSIS from SYNTHETIC EXPERIMENTS with CaLDAS



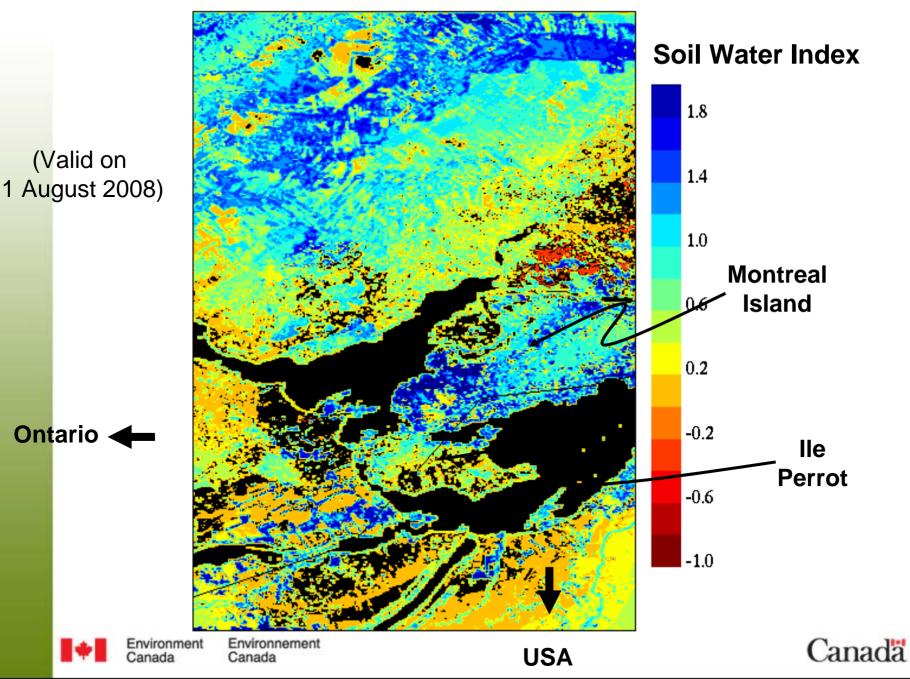
Research Themes and Applications

- Different sources of information and observations related to soil moisture at varying temporal scales and spatial resolutions.
 - SMOS/SMAP lower-resolution radiometer data (~ 40 km);
 - Screen-level observations of temperature and humidity at higher temporal frequency;
 - Radarsat-2 C-band SAR data ;
 - Higher-resolution active radar measurements from SMAP;
- Challenge is to develop methods and algorithms to optimally combine these different types of information.
- <u>Incremental CaLDAS</u> : Development of an incremental version of CaLDAS. Combination of a high-resolution land-surface model firstguess with the application of lower resolution analysis increments.
- Joint assimilation of passive and active L-band soil moisture measurements.





HIGH-RESOLUTION MODELING of SOIL MOISTURE (120m)

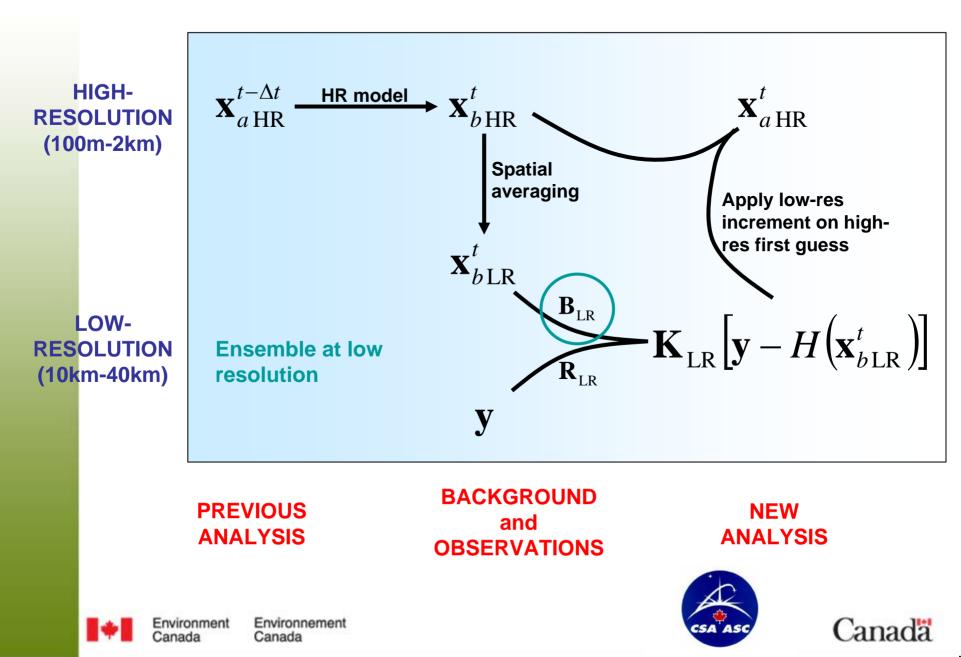


HIGH-RESOLUTION MODELING of TERRESTRIAL SNOW (1km)

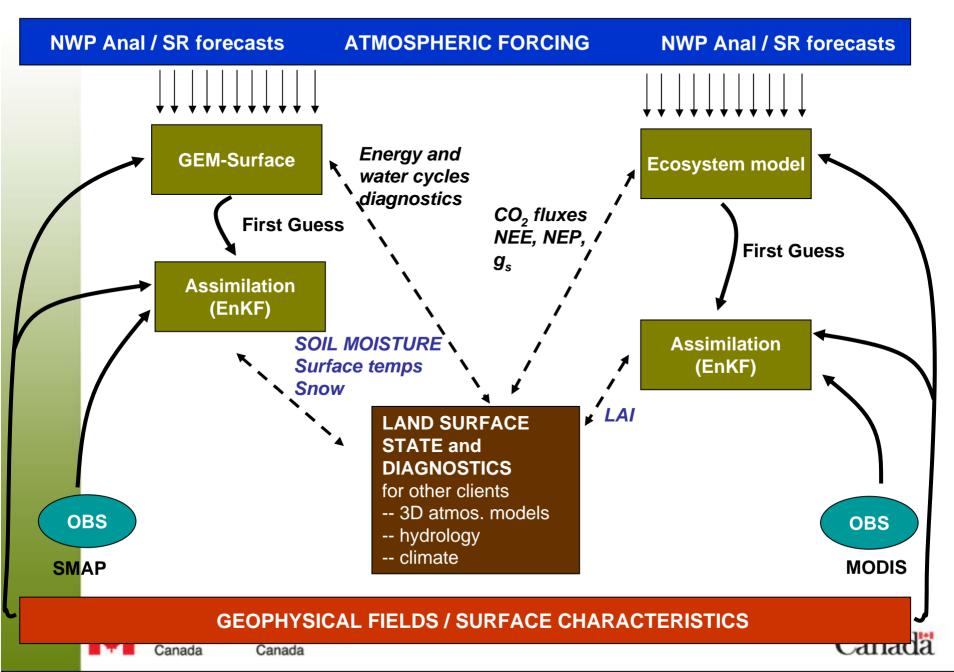
SWE(mm) SWE(mm) Alberta Alberta x 10 x 10 40.00 40.00 30.00 30.00 Winter 20.00 20.00 2005/2006 15.00 15.00 10.00 10.00 0.00 0.00 GEM-15 GEM-1 1000 1000 d b R = 0.30R = 0.70900 900 bias = -29.60bias = -189.39800 800 (mm) Simulated SWE (mm) 700 700 15 December - 31 January
February
March Simulated SWE 600 600 April 1 May - 15 June 500 500 400 400 300 300 200 200 100 100 0 300 400 500 600 700 800 900 1000 400 500 600 700 800 900 1000 100 200 300 Observed SWE (mm) Observed SWE (mm)

Mean Snow Water Equivalent

INCREMENTAL VERSION of CALDAS



Future Land-Surface Modeling and Data Assimilation System



SMOS TB 40° H-pol 1015 UTC 11 June 2010

Environment Canada has been receiving the SMOS near real-time BUFR data since March 2010. These data will be assimilated within CaLDAS.

